

Rowspace

Definition: Given an $m \times n$ matrix A , the **rowspace** of A is the subspace spanned by the rows of A (regarded as vectors) and is denoted $\text{Row}(A)$.

Example

Let $A = \begin{bmatrix} 2 & 4 & 0 & -4 \\ -3 & -1 & 5 & -4 \end{bmatrix}$, then $\text{Row}(A) = \text{Span} \left\{ \begin{bmatrix} 2 \\ 4 \\ 0 \\ -4 \end{bmatrix}, \begin{bmatrix} -3 \\ -1 \\ 5 \\ -4 \end{bmatrix} \right\}$.

We see that $\begin{bmatrix} 1 \\ -3 \\ -5 \\ 8 \end{bmatrix} \in \text{Row}(A)$, since $-\begin{bmatrix} 2 \\ 4 \\ 0 \\ -4 \end{bmatrix} - \begin{bmatrix} -3 \\ -1 \\ 5 \\ -4 \end{bmatrix} = \begin{bmatrix} 1 \\ -3 \\ -5 \\ 8 \end{bmatrix}$.

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We see that $\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} \notin \text{Row}(A)$ by looking for solutions to the vector equation $t_1 \begin{bmatrix} 2 \\ 4 \\ 0 \\ -4 \end{bmatrix} + t_2 \begin{bmatrix} -3 \\ -1 \\ 5 \\ -4 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$.

We will create the augmented matrix, and row reduce.

$$\left[\begin{array}{ccc|c} 2 & -3 & 1 & 1 \\ 4 & -1 & 2 & 2 \\ 0 & 5 & 3 & 3 \\ -4 & -4 & 4 & 4 \end{array} \right] \xrightarrow{\substack{R_2 - 2R_1 \\ R_4 + 2R_1}} \sim \left[\begin{array}{ccc|c} 2 & -3 & 1 & 1 \\ 0 & 5 & 0 & 0 \\ 0 & 5 & 3 & 3 \\ 0 & -10 & 6 & 6 \end{array} \right] \xrightarrow{\substack{R_3 - R_2 \\ R_4 + 2R_2}} \sim \left[\begin{array}{ccc|c} 2 & -3 & 1 & 1 \\ 0 & 5 & 0 & 0 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 6 & 6 \end{array} \right]$$

The last two rows are bad rows, so our vector equation does not have any solutions.

This means that $\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$ is not in $\text{Row}(A)$.

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Note: There is no counterpart to the rowspace in the world of linear mappings, but if we recall that the transpose of a matrix interchanges the rows and columns, we get that

$$\text{Row}(A) = \{A^T \vec{x} \in \mathbb{R}^n \mid \vec{x} \in \mathbb{R}^m\}, \text{ or } \text{Row}(A) = \text{Col}(A^T)$$

Theorem 3.4.4

If the $m \times n$ matrix A is row equivalent to the matrix B , then $\text{Row}(A) = \text{Row}(B)$.

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Example

Let $A = \begin{bmatrix} 2 & 4 & 0 \\ 3 & 6 & -3 \\ 4 & 4 & 8 \end{bmatrix}$. Then we notice that:

$$\begin{aligned} \begin{bmatrix} 2 & 4 & 0 \\ 3 & 6 & -3 \\ 4 & 4 & 8 \end{bmatrix} &\xrightarrow{\substack{(1/2)R_1 \\ -(1/3)R_2 \\ -(1/4)R_3}} \begin{bmatrix} 1 & 2 & 0 \\ -1 & -2 & 1 \\ -1 & -1 & -2 \end{bmatrix} \xrightarrow{\substack{R_2 + R_1 \\ R_3 + R_1}} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & -2 \end{bmatrix} \xrightarrow{R_2 \uparrow R_3} \sim \\ \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} &\xrightarrow{R_2 + 2R_3} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 - 2R_2} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \end{aligned}$$

So we see that A is row equivalent to I_3 .

By Theorem 3.4.4, this means that $\text{Row}(A) = \text{Row}(I_3) = \text{Span}\left\{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right\} = \mathbb{R}^3$.

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Theorem 3.4.4

If the $m \times n$ matrix A is row equivalent to the matrix B , then $\text{Row}(A) = \text{Row}(B)$.

Proof

To prove the theorem, we need to look at the effect of each type of elementary row operation on the row space.

Type 1: Interchanging two rows.

Suppose we obtain B from A by interchanging two rows of A .

Since vector addition is commutative, changing the order we list the vectors does not change the span, so

$\text{Row}(B) = \text{Row}(A)$.

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Type 2: Multiplying row i by a non-zero scalar s .

Let $\vec{a}_1^T, \vec{a}_2^T, \dots, \vec{a}_m^T$ be the rows of A , such that $\text{Row}(A) = \text{Span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_m\}$

Also let $\vec{a}_1^T, \vec{a}_2^T, \dots, s\vec{a}_i^T, \dots, \vec{a}_m^T$ be the rows of B .

We then get that

$$\begin{aligned} \text{Row}(B) &= \text{Span}\{\vec{a}_1, \vec{a}_2, \dots, s\vec{a}_i, \dots, \vec{a}_m\} \\ &= \{t_1\vec{a}_1 + t_2\vec{a}_2 + \dots + t_i(s\vec{a}_i) + \dots + t_m\vec{a}_m \mid t_j \in \mathbb{R}\} \\ &= \{t_1\vec{a}_1 + t_2\vec{a}_2 + \dots + (t_i s)\vec{a}_i + \dots + t_m\vec{a}_m \mid t_j \in \mathbb{R}\} \\ &= \text{Span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_i, \dots, \vec{a}_m\} \\ &= \text{Row}(A) \end{aligned}$$

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Type 3: Adding s times the i -th row to the j -th row.

Let $\vec{a}_1^T, \vec{a}_2^T, \dots, \vec{a}_m^T$ be the rows of A , so that $\text{Row}(A) = \text{Span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_m\}$

Also let $\vec{a}_1^T, \vec{a}_2^T, \dots, \vec{a}_j^T + s\vec{a}_i^T, \dots, \vec{a}_m^T$ be the rows of B

We then get that

$$\begin{aligned} \text{Row}(B) &= \text{Span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_j + s\vec{a}_i, \dots, \vec{a}_m\} \\ &= \{t_1\vec{a}_1 + t_2\vec{a}_2 + \dots + t_i\vec{a}_i + \dots + t_j(\vec{a}_j + s\vec{a}_i) + \dots + t_m\vec{a}_m \mid t_k \in \mathbb{R}\} \\ &= \{t_1\vec{a}_1 + t_2\vec{a}_2 + \dots + (t_i + st_j)\vec{a}_i + \dots + (t_js)\vec{a}_j + \dots + t_m\vec{a}_m \mid t_k \in \mathbb{R}\} \\ &= \text{Span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_i, \dots, \vec{a}_j, \dots, \vec{a}_m\} \\ &= \text{Row}(A) \end{aligned}$$

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